

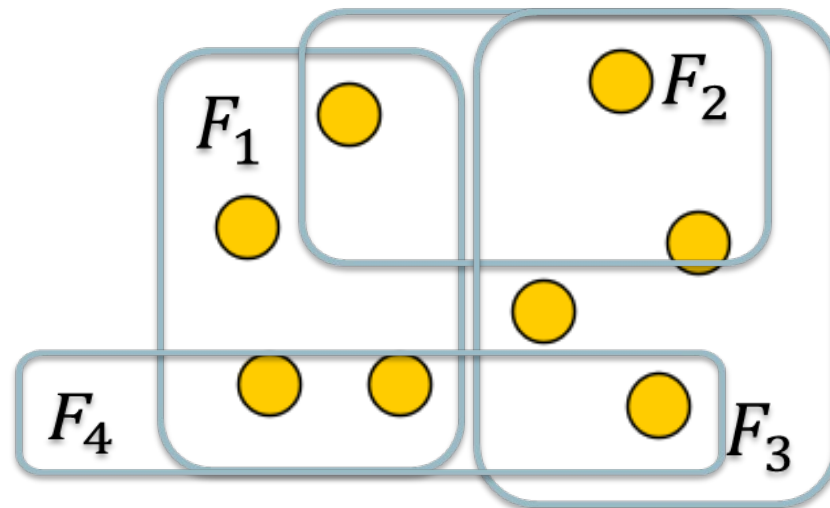
DYNAMIC PROGRAMMING

Slides from Prof. Daniel Marx

The SET COVER problem

• **Input:** A set family \mathcal{F} over a universe U and an integer k
Parameter: $|U|$
Question: Is there a subfamily $\mathcal{F}' \subseteq \mathcal{F}$ of at most k sets, such that $\bigcup_{F \in \mathcal{F}'} F = U$?

- The subfamily \mathcal{F}' **covers** the universe U
- SET COVER parameterized by the universe size is FPT
 - Algorithm with running time $2^{|U|} \cdot (|U| + |\mathcal{F}|)^c$
 - Based on **dynamic programming**



Dynamic programming for SET COVER

- Let $\mathcal{F} = \{F_1, F_2, \dots, F_m\}$
- We define a DP table for $X \subseteq U$ and $j \in \{0, 1, \dots, m\}$
 $T[X, j] = \min \text{ nr. of sets from } F_1, \dots, F_j \text{ needed to cover } X$
Or $+\infty$ if impossible
- The value $T[U, m]$ gives the minimum size of a set cover
 - To solve the problem, compute T using base cases and a recurrence

Filling the dynamic programming table

- $T[X, j] = \min$ nr. of sets from F_1, \dots, F_j needed to cover X

Base case: $j = 0$

$$T[X, j] = 0 \text{ if } X = \emptyset, \text{ otherwise it is } +\infty$$

Recursive step: $j > 0$

$$T[X, j] = \min(T[X, j - 1], 1 + T[X \setminus F_j, j - 1])$$

- Skip set F_j , or pay for F_j and afterwards cover $X \setminus F_j$
- Each entry can be computed in polynomial time
 - $(|\mathcal{F}| + 1) \cdot 2^{|U|}$ entries in total

More on dynamic programming

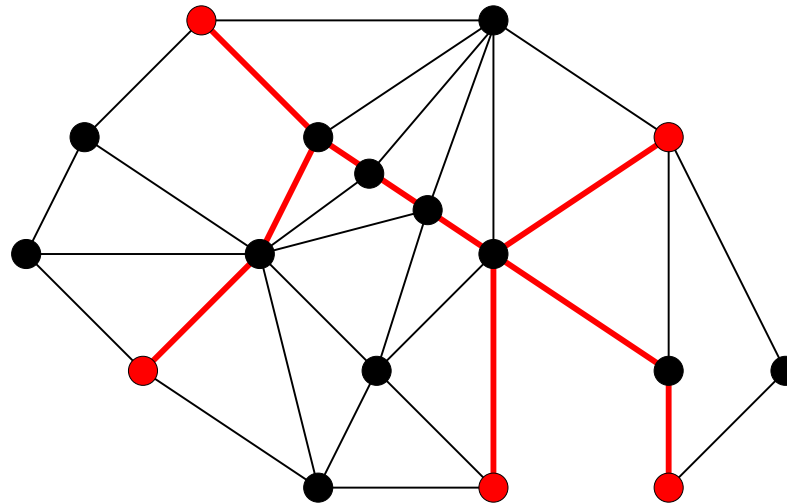
- Dynamic programming is a memory-intensive algorithmic paradigm that yields FPT algorithms in various situations
 - Here: dynamic programming over **subsets** of U
 - Later: dynamic programming over **tree decompositions**
- Research challenge:
 - Determine whether the $2^{|U|}$ factor can be improved to $(2 - \epsilon)^{|U|}$ for some $\epsilon > 0$

STEINER TREE



STEINER TREE

Task: Given a graph G with weighted edges and a set S of k vertices, find a tree T of minimum weight that contains S .



Known to be NP-hard. For fixed k , we can solve it in polynomial time: we can guess the Steiner points and the way they are connected.

Theorem: STEINER TREE is FPT parameterized by $k = |S|$.

STEINER TREE

Solution by dynamic programming. For $v \in V(G)$ and $X \subseteq S$,

$c(v, X) :=$ minimum cost of a Steiner tree of X that contains v

$d(u, v) :=$ distance of u and v

Recurrence relation:

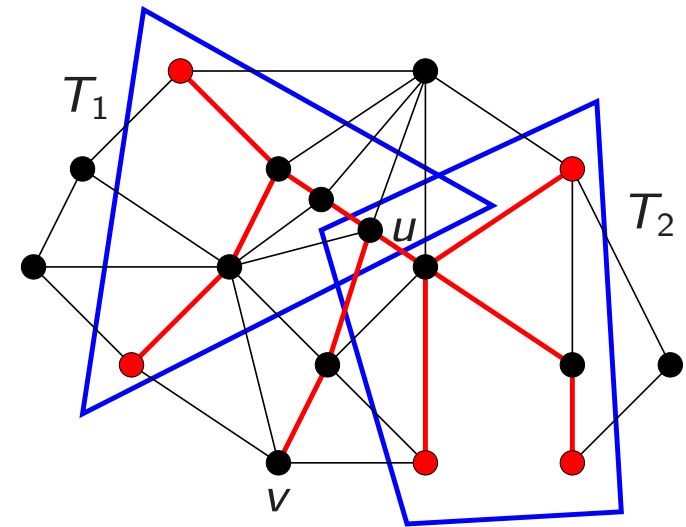
$$c(v, X) = \min_{\substack{u \in V(G) \\ \emptyset \subset X' \subset X}} c(u, X' \setminus u) + c(u, (X \setminus X') \setminus u) + d(u, v)$$

STEINER TREE

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⑥ \leq : A tree T_1 realizing $c(u, X' \setminus u)$, a tree T_2 realizing $c(u, (X \setminus X') \setminus u)$, and the path uv gives a (superset of a) Steiner tree of X containing v .

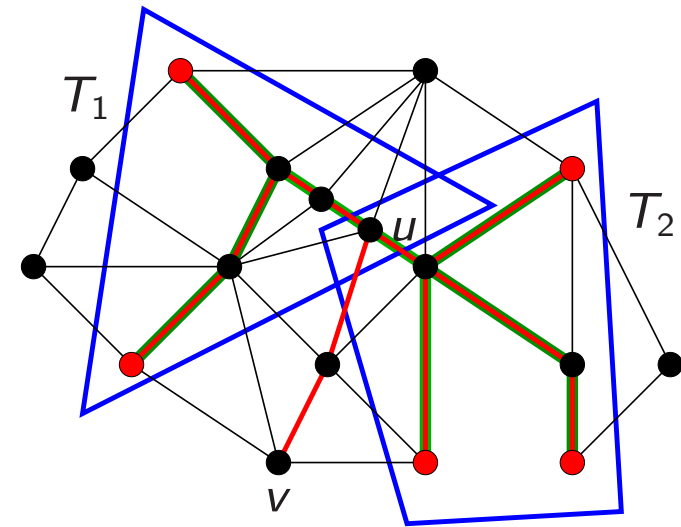


STEINER TREE

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⑥ \geq : Suppose T realizes $c(v, X)$, let T' be the minimum subtree containing X . Let u be a vertex of T' closest to v . If $|X| > 1$, then there is a component C of $T \setminus u$ that contains a subset $\emptyset \subset X' \subset X$ of terminals. Thus T is the disjoint union of a tree containing $X' \setminus u$ and u , a tree containing $(X \setminus X') \setminus u$ and u , and the path uv .



STEINER TREE

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Running time:

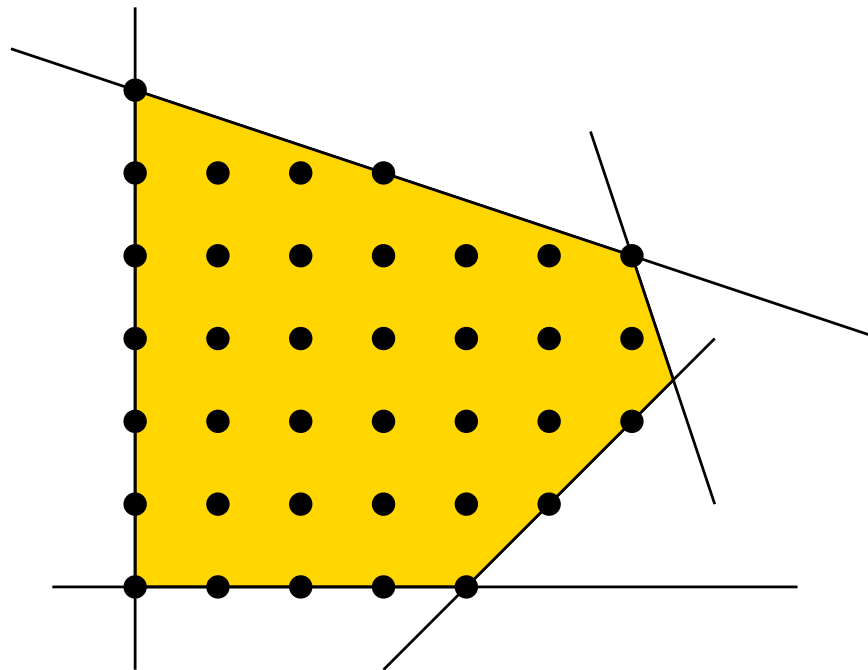
$2^k |V(G)|$ variables $c(v, X)$, determine them in increasing order of $|X|$. Variable $c(v, X)$ can be determined by considering $2^{|X|}$ cases. Total number of cases to consider:

$$\sum_{X \subseteq T} 2^{|X|} = \sum_{i=1}^k \binom{k}{i} 2^i \leq (1+2)^k = 3^k.$$

Running time is $O^*(3^k)$.

Note: Running time can be reduced to $O^*(2^k)$ with clever techniques.

Integer Linear Programming



Integer Linear Programming

Linear Programming (LP): important tool in (continuous) combinatorial optimization. Sometimes very useful for discrete problems as well.

$$\max c_1x_1 + c_2x_2 + c_3x_3$$

s.t.

$$x_1 + 5x_2 - x_3 \leq 8$$

$$2x_1 - x_3 \leq 0$$

$$3x_2 + 10x_3 \leq 10$$

$$x_1, x_2, x_3 \in \mathbb{R}$$

Fact: It can be decided if there is a solution (feasibility) and an optimum solution can be found in polynomial time.

Integer Linear Programming

Integer Linear Programming (ILP): Same as LP, but we require that every x_i is integer.

Very powerful, able to model many NP-hard problems. (Of course, no polynomial-time algorithm is known.)

Theorem: ILP with p variables can be solved in time $p^{O(p)} \cdot n^{O(1)}$.

CLOSEST STRING

Task: Given strings s_1, \dots, s_k of length L over alphabet Σ , and an integer d , find a string s (of length L) such that $d(s, s_i) \leq d$ for every $1 \leq i \leq k$.

Note: $d(s, s_i)$ is the Hamming distance.

Theorem: CLOSEST STRING parameterized by k is FPT.

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Theorem: CLOSEST STRING parameterized by L is FPT.

Theorem: CLOSEST STRING is NP-hard for $\Sigma = \{0, 1\}$.

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CLOSEST STRING

An instance with $k = 5$ and a solution for $d = 4$:

s_1	CBDCCACBB
s_2	ABDBCABDB
s_3	CDDBACCB
s_4	DDABACCB
s_5	ACDBDDCBC
<hr/>	
	ADDBCACB

Each column can be described by a partition \mathcal{P} of $[k]$.

The instance can be described by an integer $c_{\mathcal{P}}$ for each partition \mathcal{P} : the number of columns with this type.

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An instance with $k = 5$ and a solution for $d = 4$:

s_1	C B D C C A C B B
s_2	A B D B C A B D B
s_3	C D D B A C C B D
s_4	D D A B A C C B D
s_5	A C D B D D C B C
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Describing a solution: If C is a class of \mathcal{P} , let $x_{\mathcal{P},C}$ be the number of type \mathcal{P} columns where the solution agrees with class C .

There is a solution iff the following ILP has a feasible solution:

$$\begin{aligned} \sum_{C \in \mathcal{P}} x_{\mathcal{P},C} &\leq c_{\mathcal{P}} && \forall \text{partition } \mathcal{P} \\ \sum_{i \notin C, C \in \mathcal{P}} x_{\mathcal{P},C} &\leq d && \forall 1 \leq i \leq k \\ x_{\mathcal{P},C} &\geq 0 && \forall \mathcal{P}, C \end{aligned}$$

Number of variables is $\leq B(k) \cdot k$, where $B(k)$ is the no. of partitions of $[k]$

\Rightarrow The ILP algorithm solves the problem in time $f(k) \cdot n^{O(1)}$.

Graph Minors



Neil Robertson



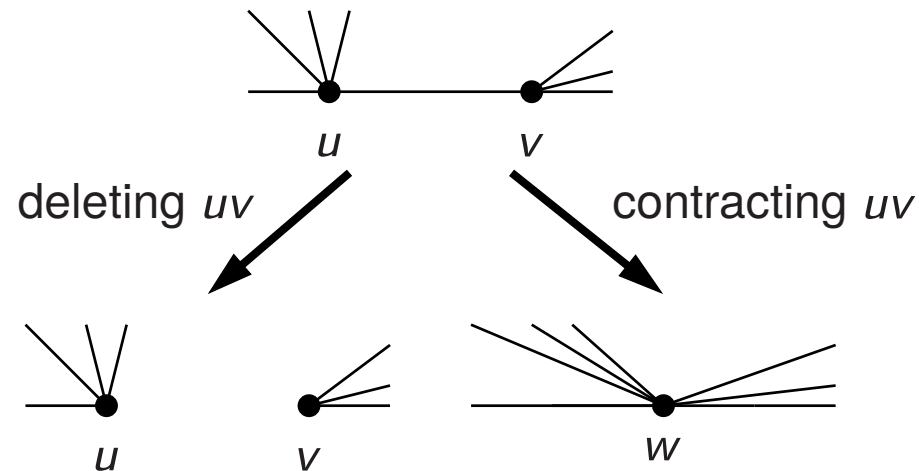
Paul Seymour

Graph Minors

- ⑥ Some consequences of the Graph Minors Theorem give a quick way of showing that certain problems are FPT.
- ⑥ However, the function $f(k)$ in the resulting FPT algorithms can be HUGE, completely impractical.
- ⑥ History: motivation for FPT.
- ⑥ Parts and ingredients of the theory are useful for algorithm design.
- ⑥ New algorithmic results are still being developed.

Graph Minors

Definition: Graph H is a **minor** G ($H \leq G$) if H can be obtained from G by deleting edges, deleting vertices, and contracting edges.

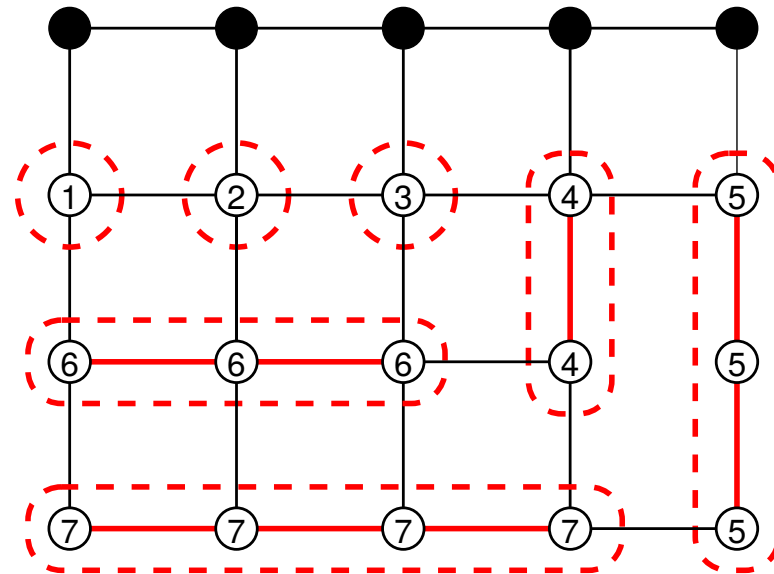
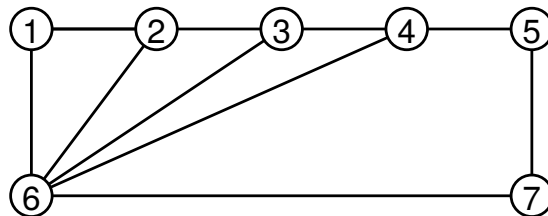


Example: A triangle is a minor of a graph G if and only if G has a cycle (i.e., it is not a forest).

Graph minors

Equivalent definition: Graph H is a **minor** of G if there is a mapping ϕ that maps each vertex of H to a connected subset of G such that

- ⑥ $\phi(u)$ and $\phi(v)$ are disjoint if $u \neq v$, and
- ⑥ if $uv \in E(G)$, then there is an edge between $\phi(u)$ and $\phi(v)$.



Minor closed properties

Definition: A set \mathcal{G} of graphs is **minor closed** if whenever $G \in \mathcal{G}$ and $H \leq G$, then $H \in \mathcal{G}$ as well.

Examples of minor closed properties:

- planar graphs
- acyclic graphs (forests)
- graphs having no cycle longer than k
- empty graphs

Examples of **not** minor closed properties:

- complete graphs
- regular graphs
- bipartite graphs

Forbidden minors

Let \mathcal{G} be a minor closed set and let \mathcal{F} be the set of “minimal bad graphs”: $H \in \mathcal{F}$ if $H \notin \mathcal{G}$, but every proper minor of H is in \mathcal{G} .

Characterization by forbidden minors:

$$G \in \mathcal{G} \iff \forall H \in \mathcal{F}, H \not\preceq G$$

The set \mathcal{F} is the **obstruction set** of property \mathcal{G} .

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Theorem: [Wagner] A graph is planar if and only if it does not have a K_5 or $K_{3,3}$ minor.

In other words: the obstruction set of planarity is $\mathcal{F} = \{K_5, K_{3,3}\}$.

Does every minor closed property have such a finite characterization?

Graph Minors Theorem

Theorem: [Robertson and Seymour] Every minor closed property \mathcal{G} has a finite obstruction set.

Note: The proof is contained in the paper series “Graph Minors I–XX”.

Note: The size of the obstruction set can be astronomical even for simple properties.

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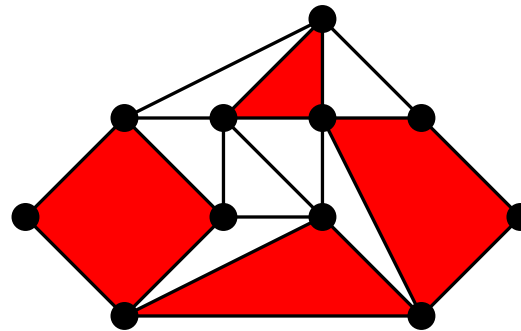
Note: The size of the obstruction set can be astronomical even for simple properties.

Theorem: [Robertson and Seymour] For every fixed graph H , there is an $O(n^3)$ time algorithm for testing whether H is a minor of the given graph G .

Corollary: For every minor closed property \mathcal{G} , there is an $O(n^3)$ time algorithm for testing whether a given graph G is in \mathcal{G} .

Applications

PLANAR FACE COVER: Given a graph G and an integer k , find an embedding of planar graph G such that there are k faces that cover all the vertices.



One line argument:

For every fixed k , the class \mathcal{G}_k of graphs of yes-instances is minor closed.

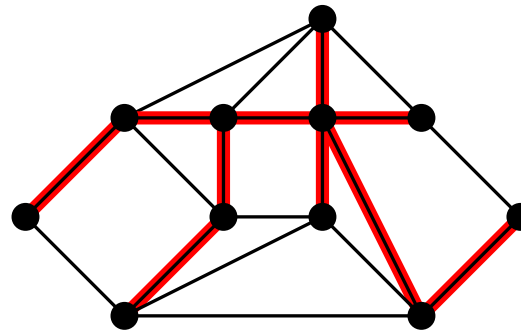


For every fixed k , there is a $O(n^3)$ time algorithm for PLANAR FACE COVER.

Note: non-uniform FPT.

Applications

k -LEAF SPANNING TREE: Given a graph G and an integer k , find a spanning tree with **at least** k leaves.



Technical modification: Is there such a spanning tree for at least one component of G ?

One line argument:

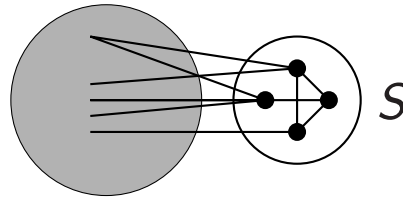
For every fixed k , the class \mathcal{G}_k of no-instances is minor closed.



For every fixed k , k -LEAF SPANNING TREE can be solved in time $O(n^3)$.

$\mathcal{G} + k$ *vertices*

Let \mathcal{G} be a graph property, and let $\mathcal{G} + kv$ contain graph G if there is a set $S \subseteq V(G)$ of k vertices such that $G \setminus S \in \mathcal{G}$.

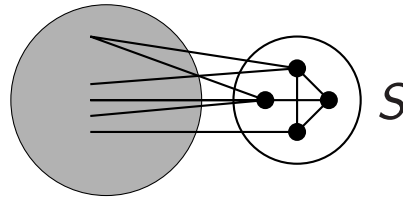


Lemma: If \mathcal{G} is minor closed, then $\mathcal{G} + kv$ is minor closed for every fixed k .

\Rightarrow It is (nonuniform) FPT to decide if G can be transformed into a member of \mathcal{G} by deleting k vertices.

$\mathcal{G} + k$ *vertices*

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- ⑥ If $\mathcal{G} = \text{forests}$ $\Rightarrow \mathcal{G} + kv = \text{graphs that can be made acyclic by the deletion of } k \text{ vertices}$ \Rightarrow FEEDBACK VERTEX SET is FPT.
- ⑥ If $\mathcal{G} = \text{planar graphs}$ $\Rightarrow \mathcal{G} + kv = \text{graphs that can be made planar by the deletion of } k \text{ vertices (} k\text{-apex graphs)}$ $\Rightarrow k\text{-APEX GRAPH is FPT.}$
- ⑥ If $\mathcal{G} = \text{empty graphs}$ $\Rightarrow \mathcal{G} + kv = \text{graphs with vertex cover number at most } k$ \Rightarrow VERTEX COVER is FPT.